



# **MATHEMATICAL CARTOGRAPHY**

**Mathematical cartography is a part of cartography, dealing with mathematical and geometrical basics of cartographic works.**

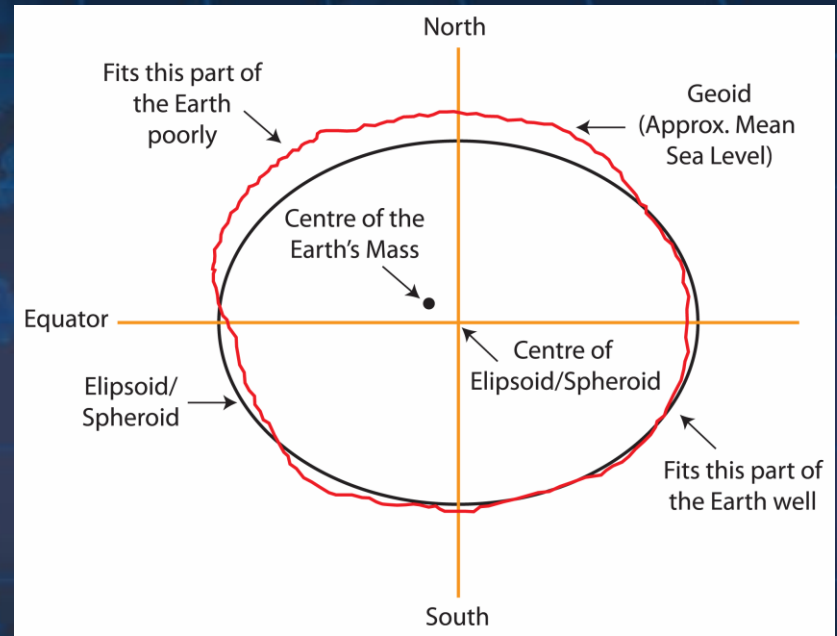
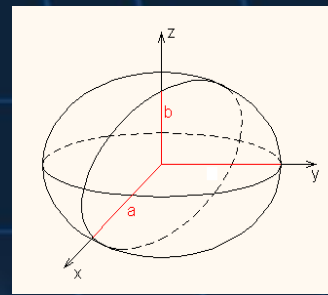
**The main goal of mathematical cartography  
– creation of a continuous planar image of the Earth**

### **Reference surfaces**

- **the real Earth is too complex in shape**
- **We need to replace the earth with a mathematically simply defined surface:**
  - **reference ellipsoid**
  - **reference sphere**
  - **plane**

## ■ Reference ellipsoid

- semimajor and semiminor axes ( $a, b$ )
- flattening  $i = (a-b) / a$  (the Earth has  $1 / i \sim 300$ )
- Bessel (1841)
- Krasovsky (1940)
- WGS84 (1984)



	<b>a</b>	<b>b</b>	<b>i</b>
<b>Bessel</b>	<b>6,377,397 m</b>	<b>6,356,079 m</b>	<b>1 : 299.15</b>
<b>Krasovsky</b>	<b>6,378,245 m</b>	<b>6,356,863 m</b>	<b>1 : 298.30</b>
<b>WGS84</b>	<b>6,378,137 m</b>	<b>6,356,752 m</b>	<b>1 : 298.26</b>

## ■ Reference sphere

- radius (R)
- for local (up to 300 km) or global ellipsoid replacement
- dual projections (ellipsoid → sphere → plane)

## ■ Plane

- geographically roughly an area up to 20×20 km
- altitude differences cannot be neglected

# Coordinate systems

- **Geographic coordinates**

- **Ellipsoid ( $\varphi, \lambda$ )**

- **Sphere ( $U, V$ )**



- **The latitude of a point P is the angle between the normal to the reference surface at the point P and the plane of the equator.**
- **The longitude of point P is the angle formed by the plane determined by the earth's axis and point P with a similar plane passing through the base point. (Ferro, Greenwich)**

- **Cartographic coordinates**

- Sphere  $(s, d)$  – instead of  $\lambda$  and  $\varphi$

These are transformed geographic coordinates using principles of the spherical trigonometry

- **3D rectangular coordinates**

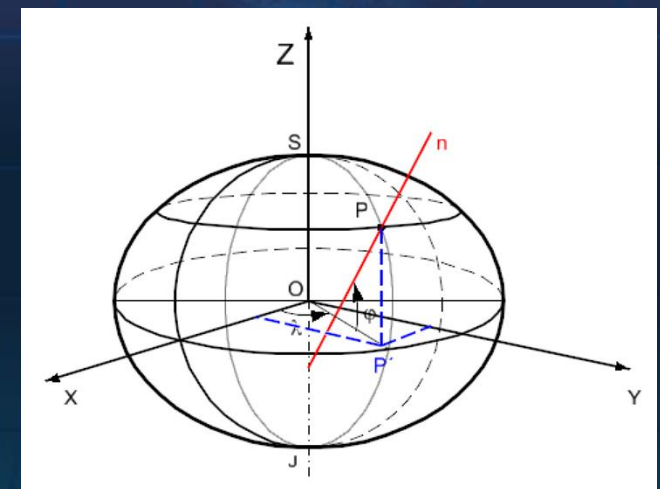
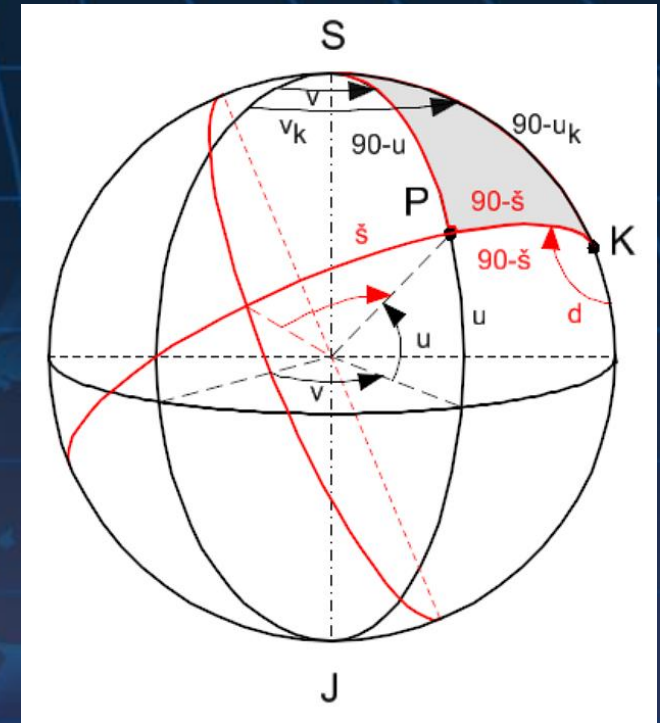
- Origin at the center of the ellipsoid

**X, Y, Z axes**

**Z in the axis of rotation of the ellipsoid**

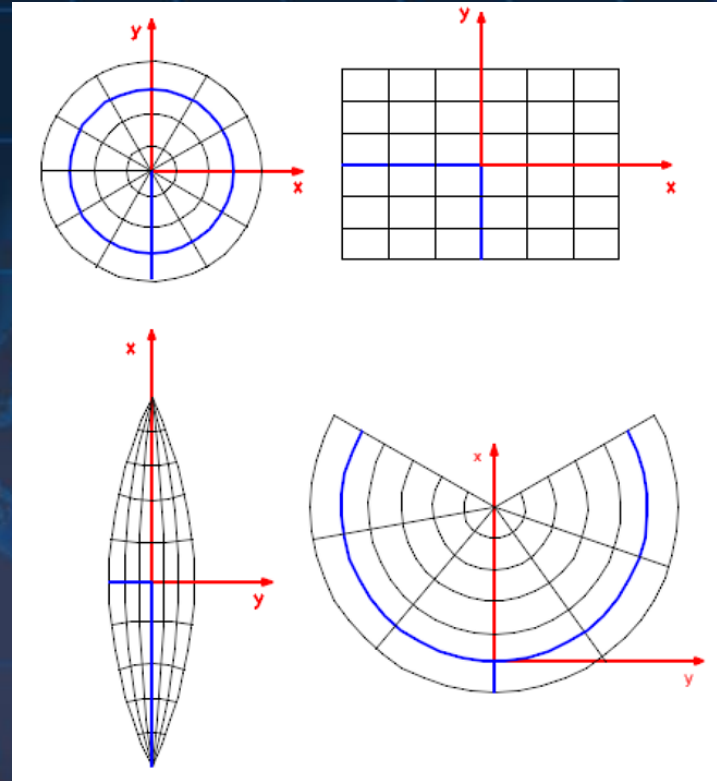
**X passes through the point where the plane of the equator intersects the prime meridian**

**Y is perpendicular to X, Z**

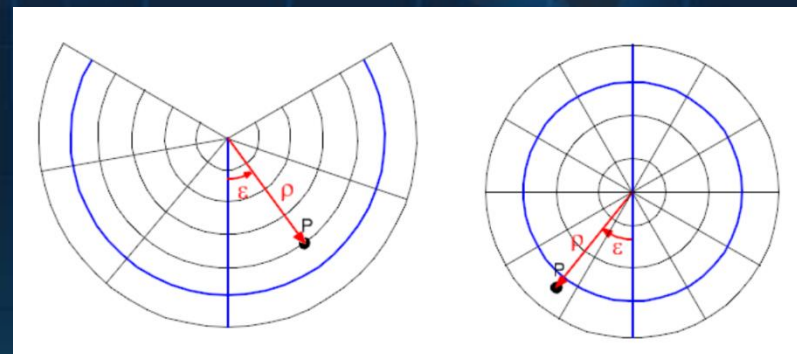


## ■ Plane coordinates

- rectangular  
 $(x, y)$

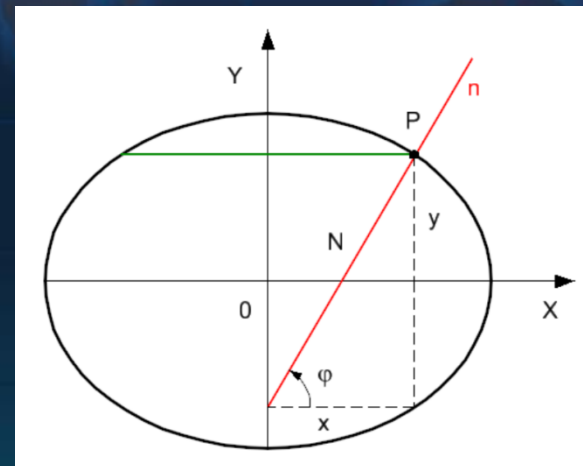
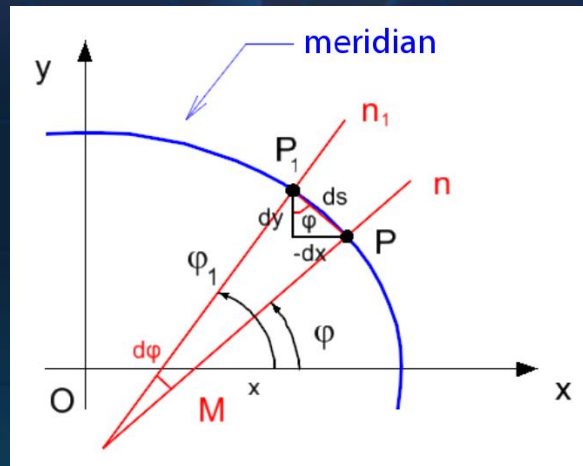
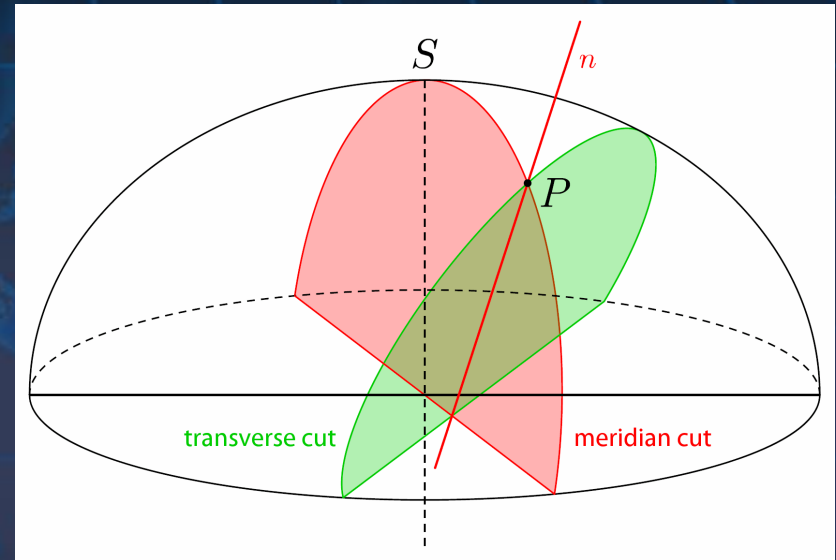


- polar  
 $(\rho, \varepsilon)$



# Curvature cuts on an ellipsoid

- Meridian cut
  - radius of curvature  $M$
- Transverse cut
  - radius of curvature  $N$





# Important curves

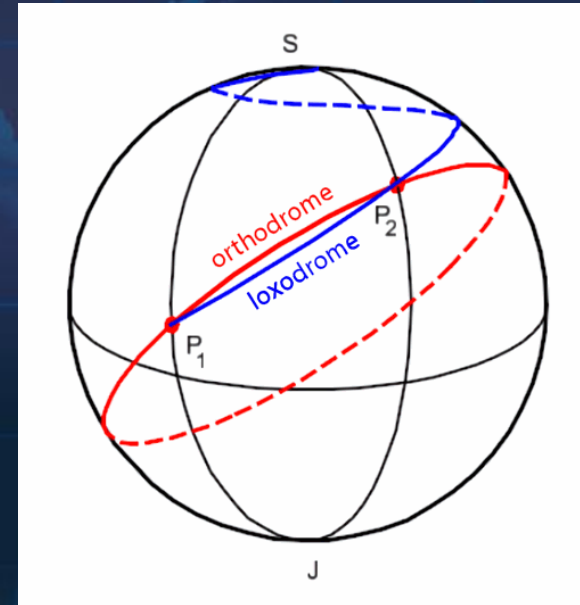
- There are important curves that follow the surface of the reference plane.
- They are used in navigation, maritime or air transport.
- In selected cartographic projections, they are shown as lines/segments, these projections were used in the past for maritime navigation.
- A **geodesic curve** (ellipsoid), on a sphere called a **great circle (orthodrome)**
- A **loxodrome**

## Loxodrome

- A curve that intersects meridians under constant azimuth  $A$ , the length is infinite.
- It is not the shortest line connecting two points on the reference surface, it is displayed as a general curve in cartographic projections.

## Orthodrome (geodetic curve)

- A closed (on a sphere) curve, representing the shortest connecting line of two points along a ref. surface.
- It is part of the great circle.
- It has infinite length on the ellipsoid.
- Clairaut's theorem applies:  
$$\cos \varphi \sin A = \cos \varphi_{MAX}$$



# Cartographic projection

- **Cartographic projection represents the mutual assignment of the position of two points on different reference surfaces.**

**(In selected cases this can be done geometrically.)**

- **The projection is uniquely given by its equations**

$$X = f(\varphi, \lambda)$$

$$Y = g(\varphi, \lambda)$$

# Cartographic distortions

- different reference surfaces have different curvature
- distortions occur during projection
- lengthwise (length ratio)  $m_A$
- area (area ratio)  $m_P$
- angular (angle difference)  $m_\omega$

# **Classification of cartographic projections**

- 1. according to projection properties (distortion)**
- 2. according to the projection area and its position**

## **1. Projections divided by distortion**

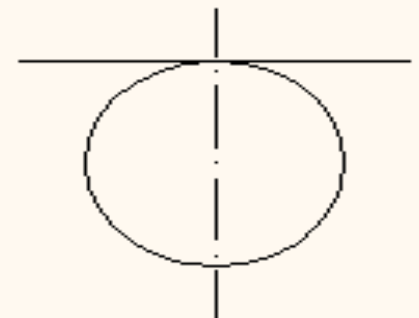
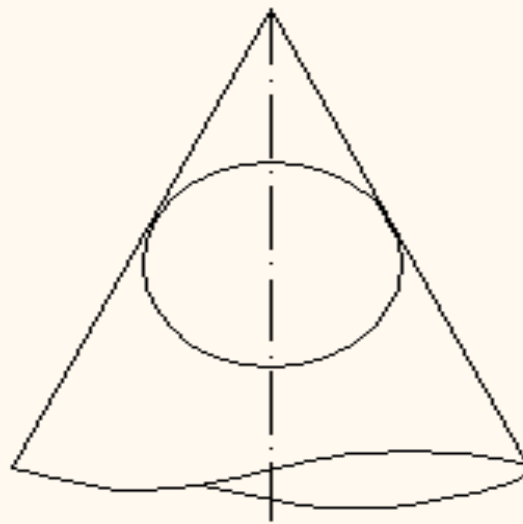
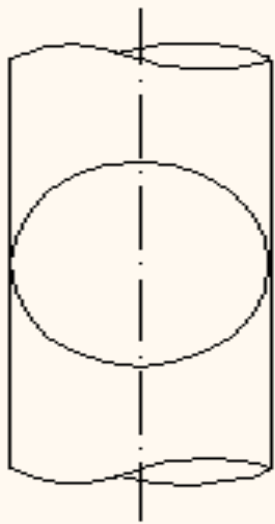
- equidistant (does not distort lengths in certain directions)**
- equivalent (does not distort surfaces)**
- conformal (does not distort angles)**

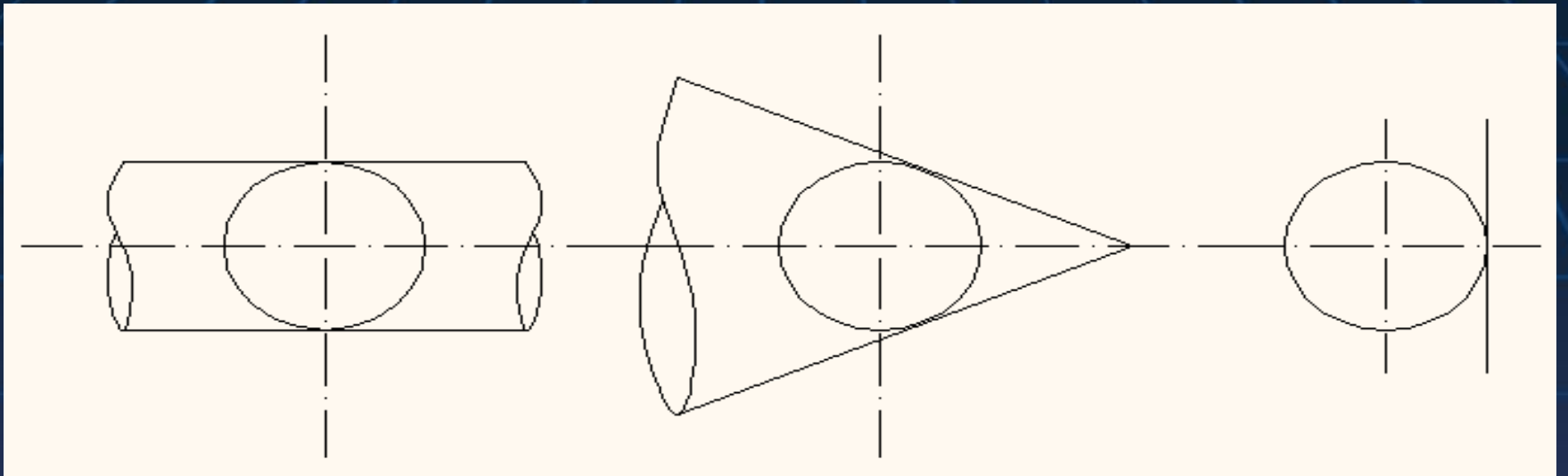
## 2. Projections divided by projection area

- **projections of an ellipsoid on a sphere**
- **simple projections (projecting on expandable surfaces)**
  - **conical, cylindrical, azimuthal**
- **pseudo-projections**
  - **conical, cylindrical, azimuthal**
- **polyconic**
- **polyhedral**
- **unclassified**

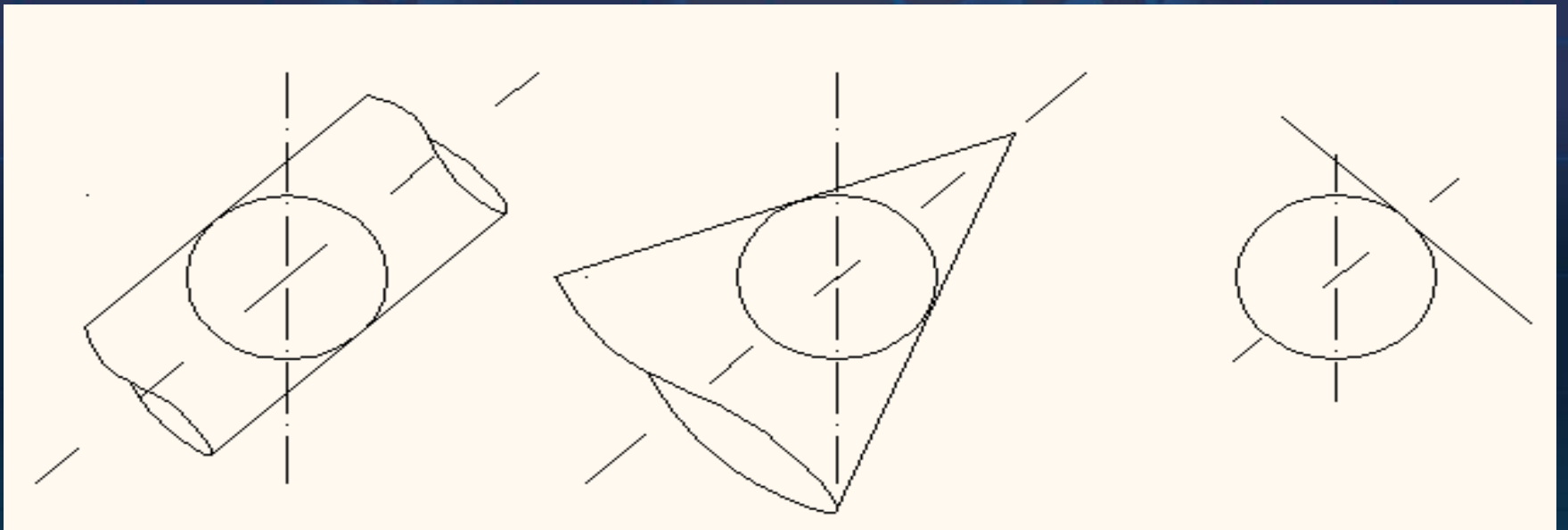
- **Simple projections according to the position of the projection area**
  - in normal position
  - in a transverse position
  - in an oblique position

Normal position





**Transverse position**



**Oblique position**



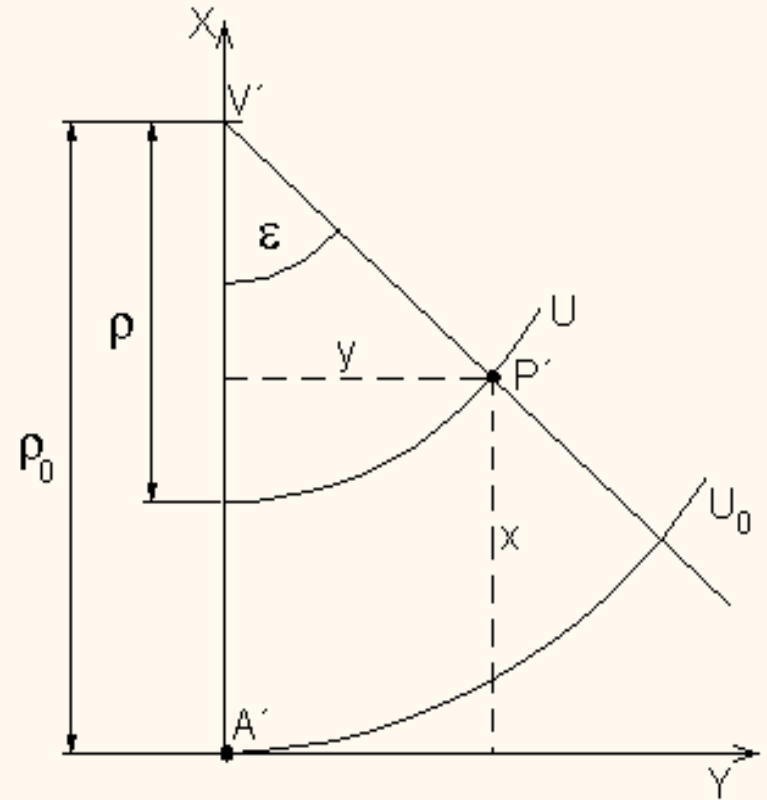
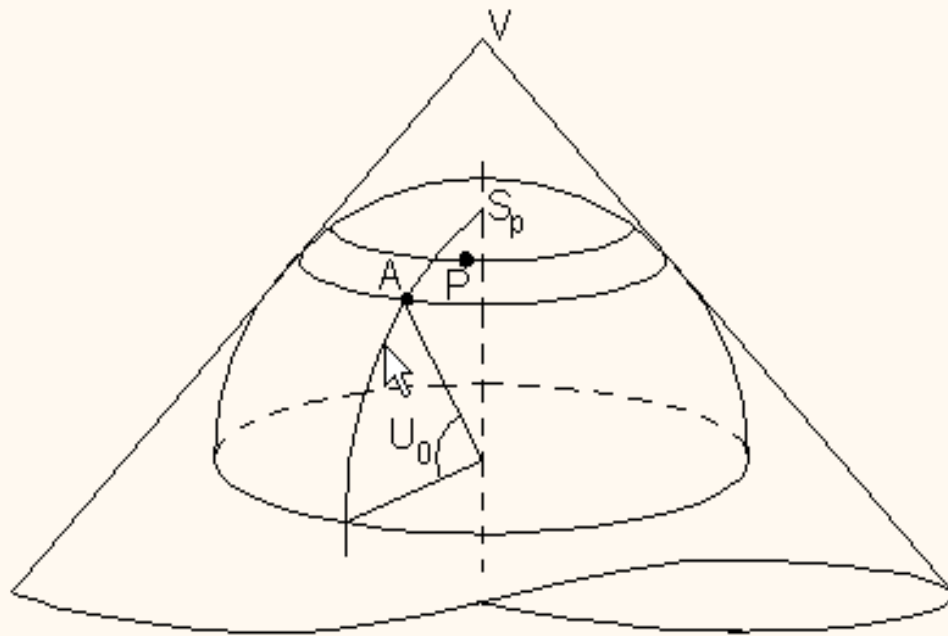
# Projection of an ellipsoid on a sphere

- **for small map scales we can replace the ellipsoid with a sphere**
- **we can choose several conditions when deriving the projection equations**
  - **preserved geographic coordinates**
  - **projection on a concentric sphere**
  - **conformity**
    - **Undistorted prime meridian condition**
    - **Preserved geographic grid**
  - **equidistant projection**
    - **In meridians**
    - **In parallels**
  - **equivalent projection**

# Simple projections

- **Plane coordinates can be expressed using a function of only one coordinate**
  - e.g. for normal position
    - $X = n V$
    - $Y = f(U)$
- **A simple rendition of cartographic meridians and parallels**
  - meridians (bundle or grid of straight lines)
  - parallels (straight lines or circles)

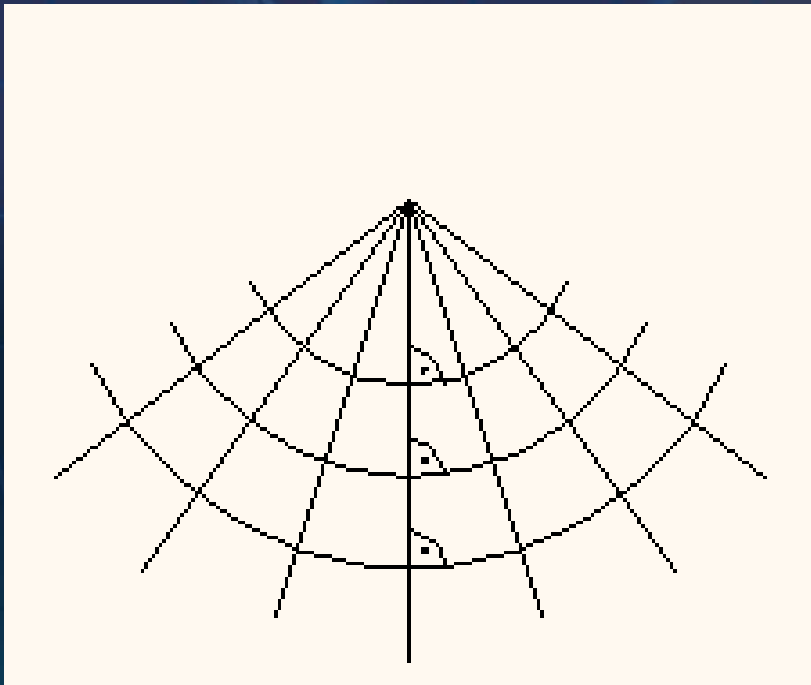
# Conical projections



- **base parallel** – approximately in the center of the area
- **prime meridian** – from which longitude is calculated

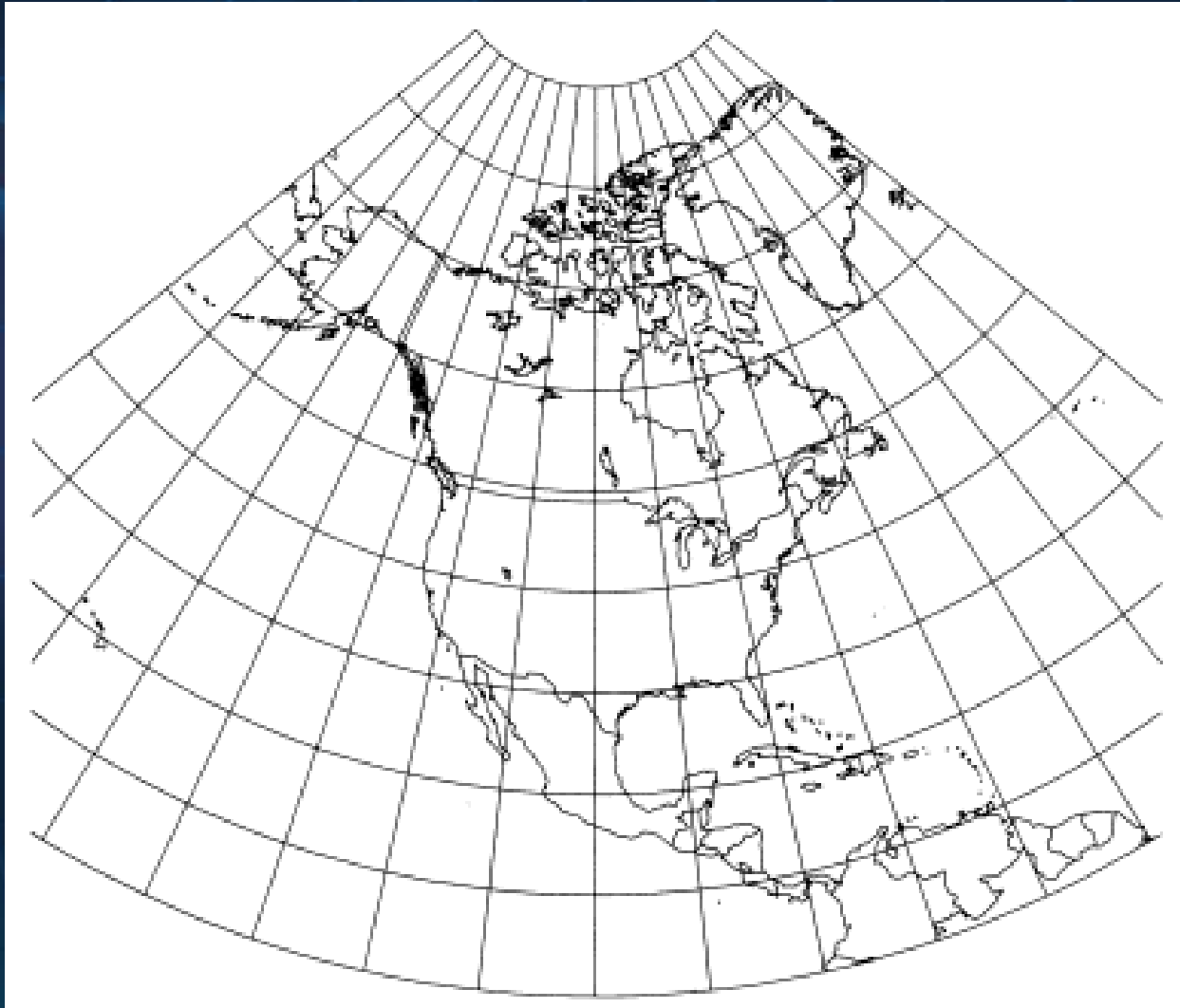
### **Geographic grid shape**

- **meridians** – a bundle of straight lines
- **parallels** – concentric circles
- **pole** – a circle or point

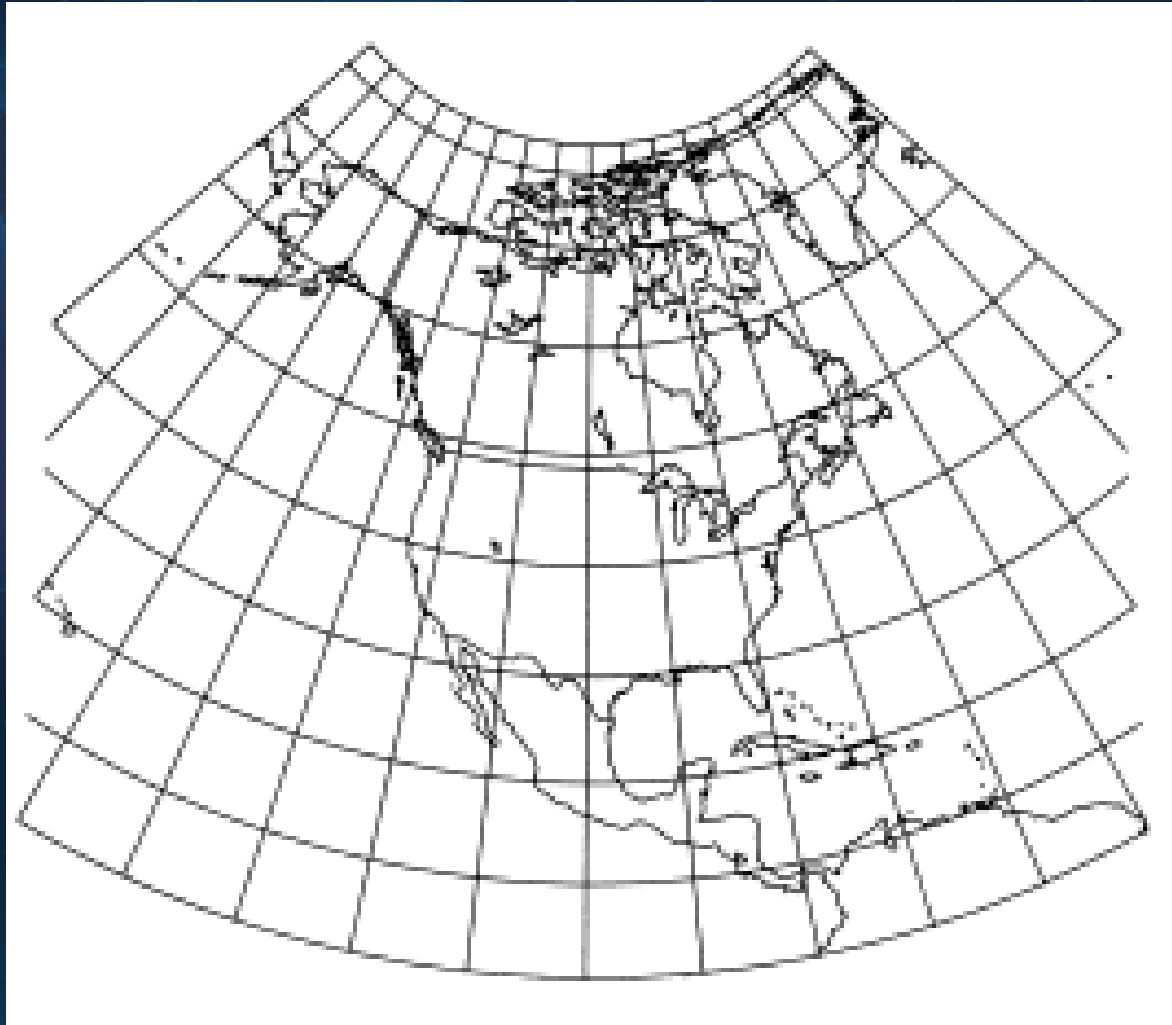


- **suitable for territories that are distributed along the small circles on the globe, e.g. spherical belts with a smaller width**
- **they are mainly used for maps of smaller scales, especially in the general position (transverse position is unsuitable, in these cases cylindrical views are preferred)**
- **on the other hand, these projections are completely unsuitable for maps of the entire world in a continuous presentation (opposite polar rendition, distortion changes)**
- **using a suitable choice of constants we get individual conic representations  
(equidistant, equivalent, conformal ×  
number of undistorted parallels, rendition of the pole)**

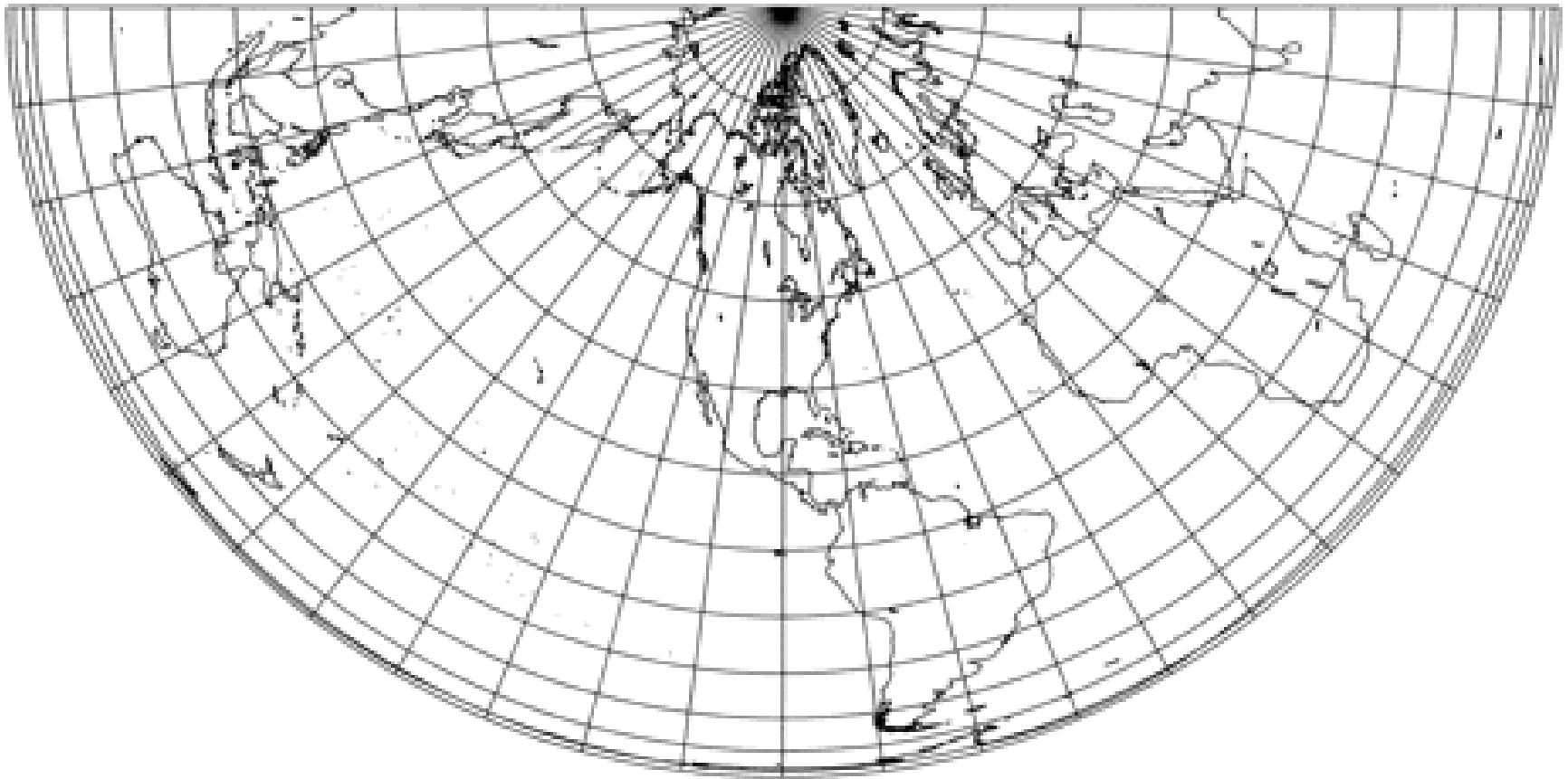
# Equidistant conic projection (in meridians) with two undistorted parallels (de l'Isle)



# Equivalent conic projection (Albers) – 2 undistorted parallels

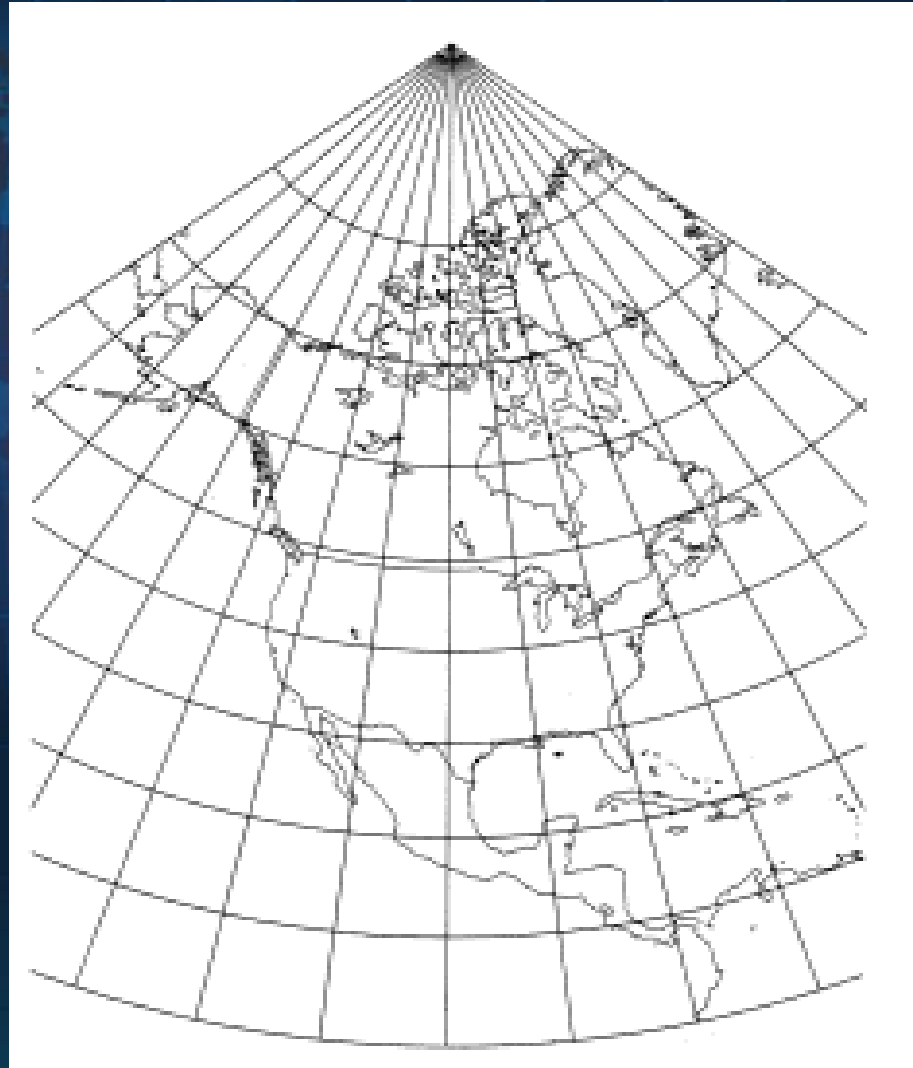


# Equivalent conic (Lambert) projection – pole as point



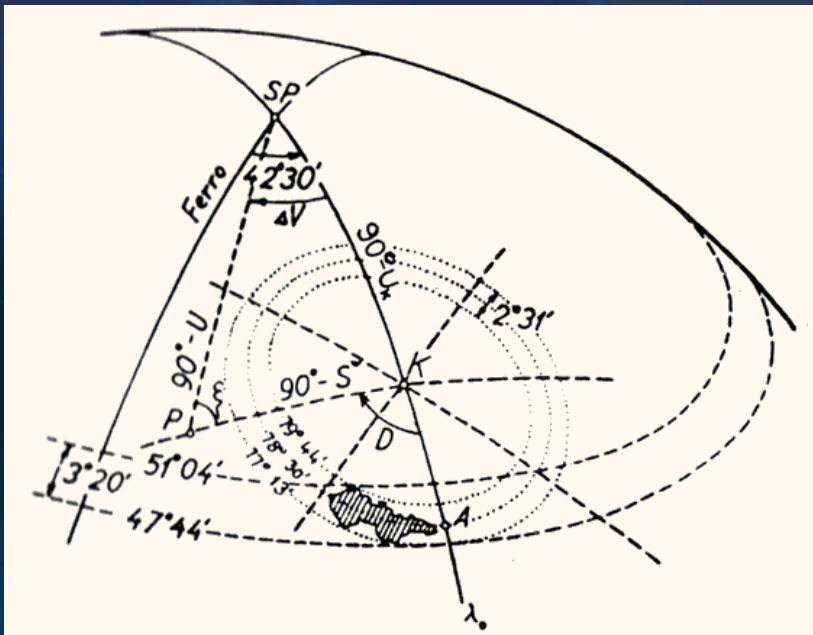


# Conformal (Lambert) conic projection



# Křovák's projection

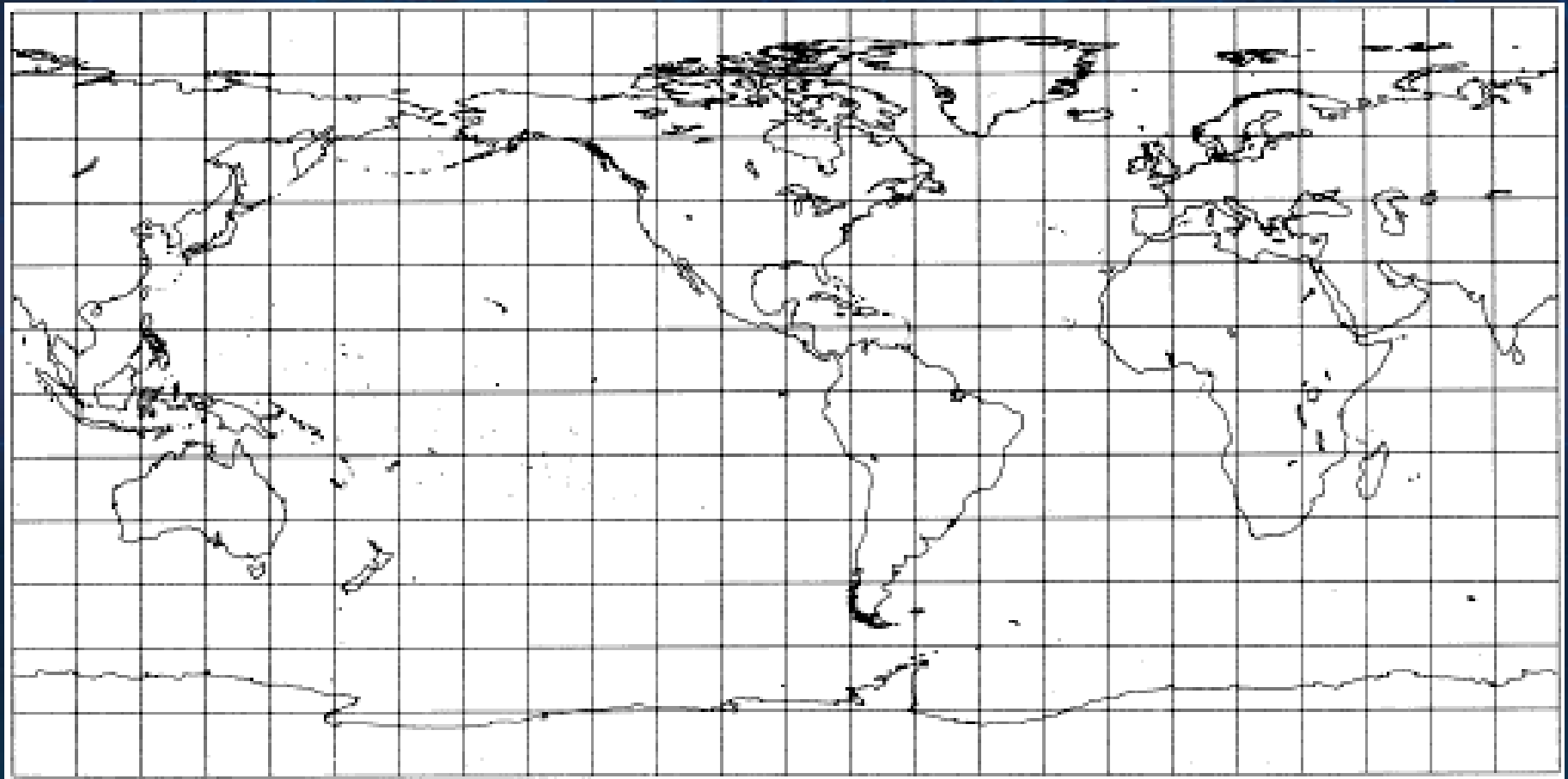
- double conformal conic projection in an oblique position
- author Ing. Josef Křovák (1922)
- became the basis of S-JTSK (a Czech system of a unified cadastral trigonometric network)



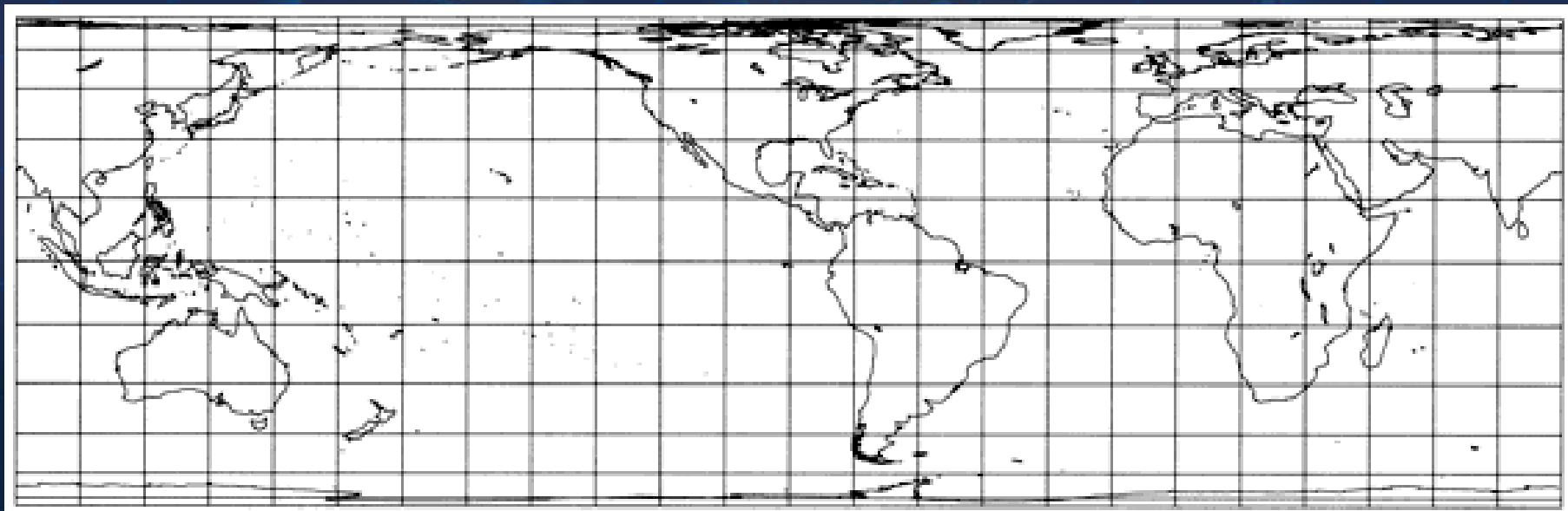
# Cylindrical projections

- equator and parallels as parallel lines
- meridians parallel lines perpendicular to the parallels
- they are suitable in the transverse position for displaying longitudinal zones or in the normal position for the belt around the equator
- the smallest distortions are achieved around the tangent circle
- on the contrary, they are completely unsuitable for displaying polar regions
- with a suitable choice of the constant, we get individual cylindrical representations  
(equidistant, equivalent, conformal × number of undistorted parallels)

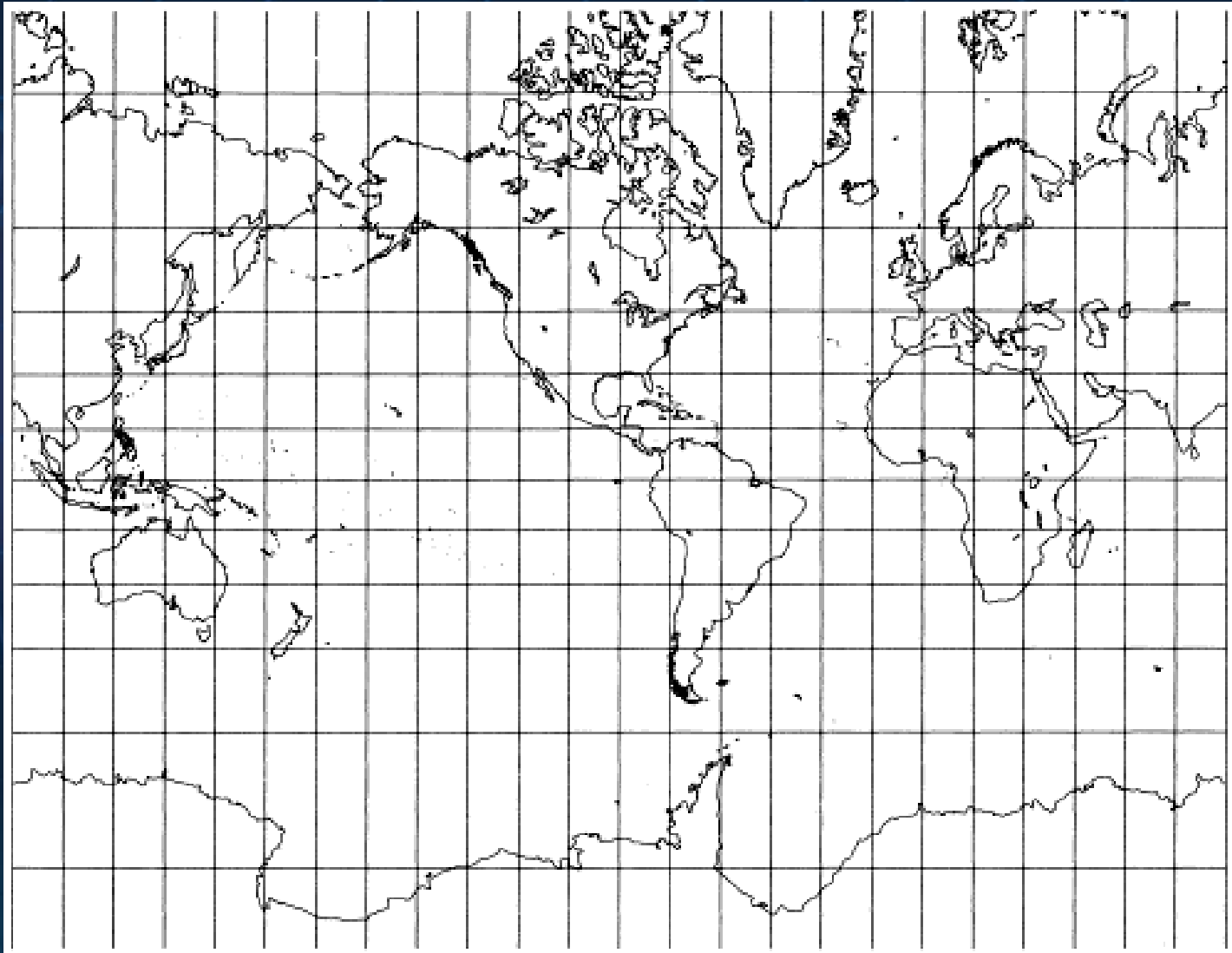
# Equidistant cylindrical projection (in meridians) with one undistorted parallel (Marinus)



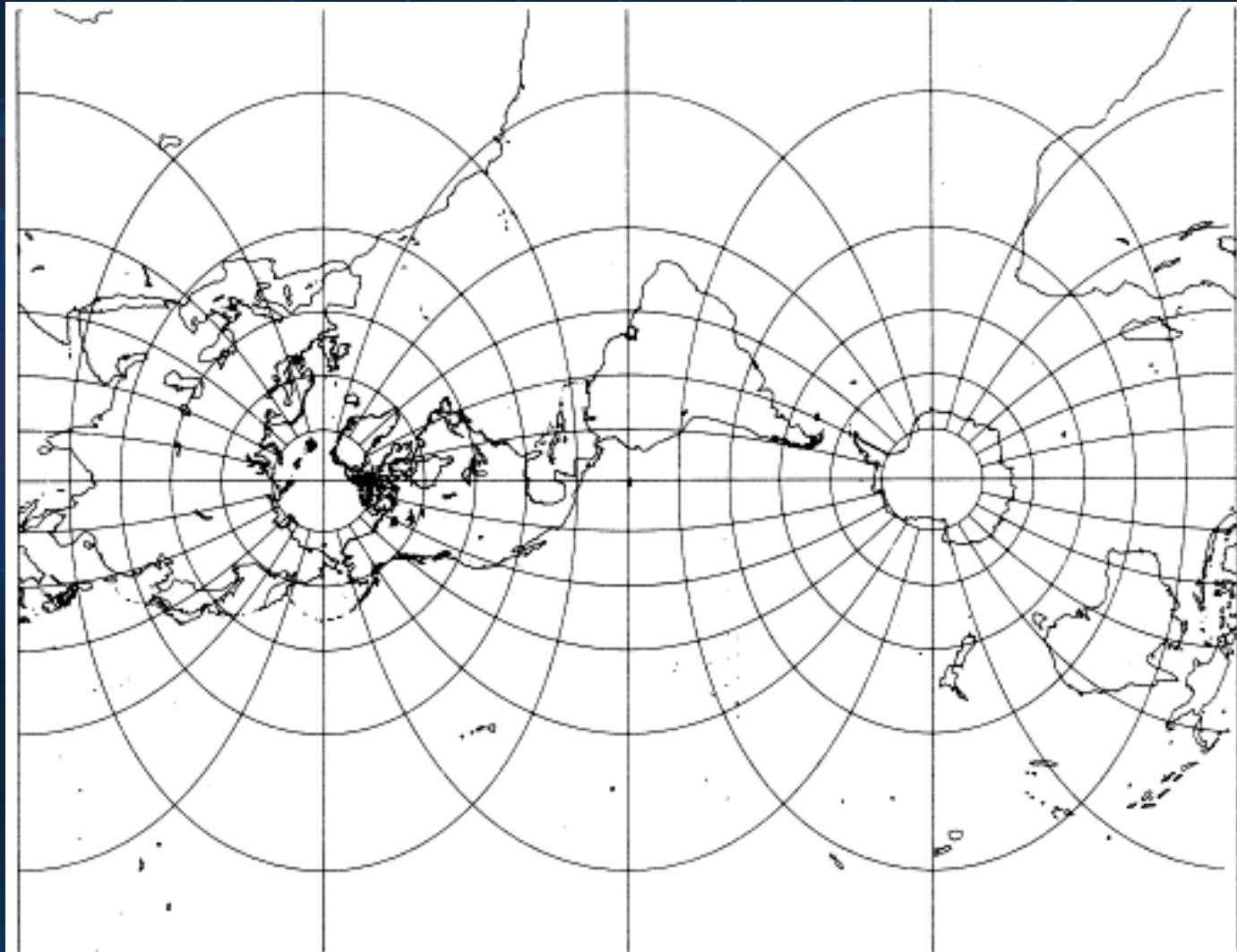
# Equivalent cylindrical projection (Lambert)



# Conformal cylindrical projection (Mercator)

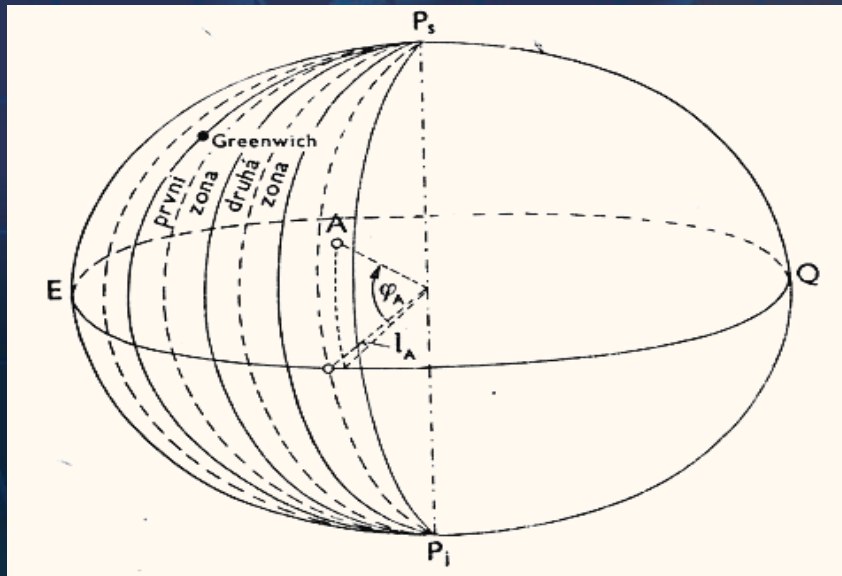


# Conformal transverse cylindrical projection (Transverse Mercator)



# Significant cylindrical projections

- Conformal cylindrical projection (Gaussian)
- Transverse conformal cylindrical projection (UTM)





# Azimuthal projection

## Geographic grid shape

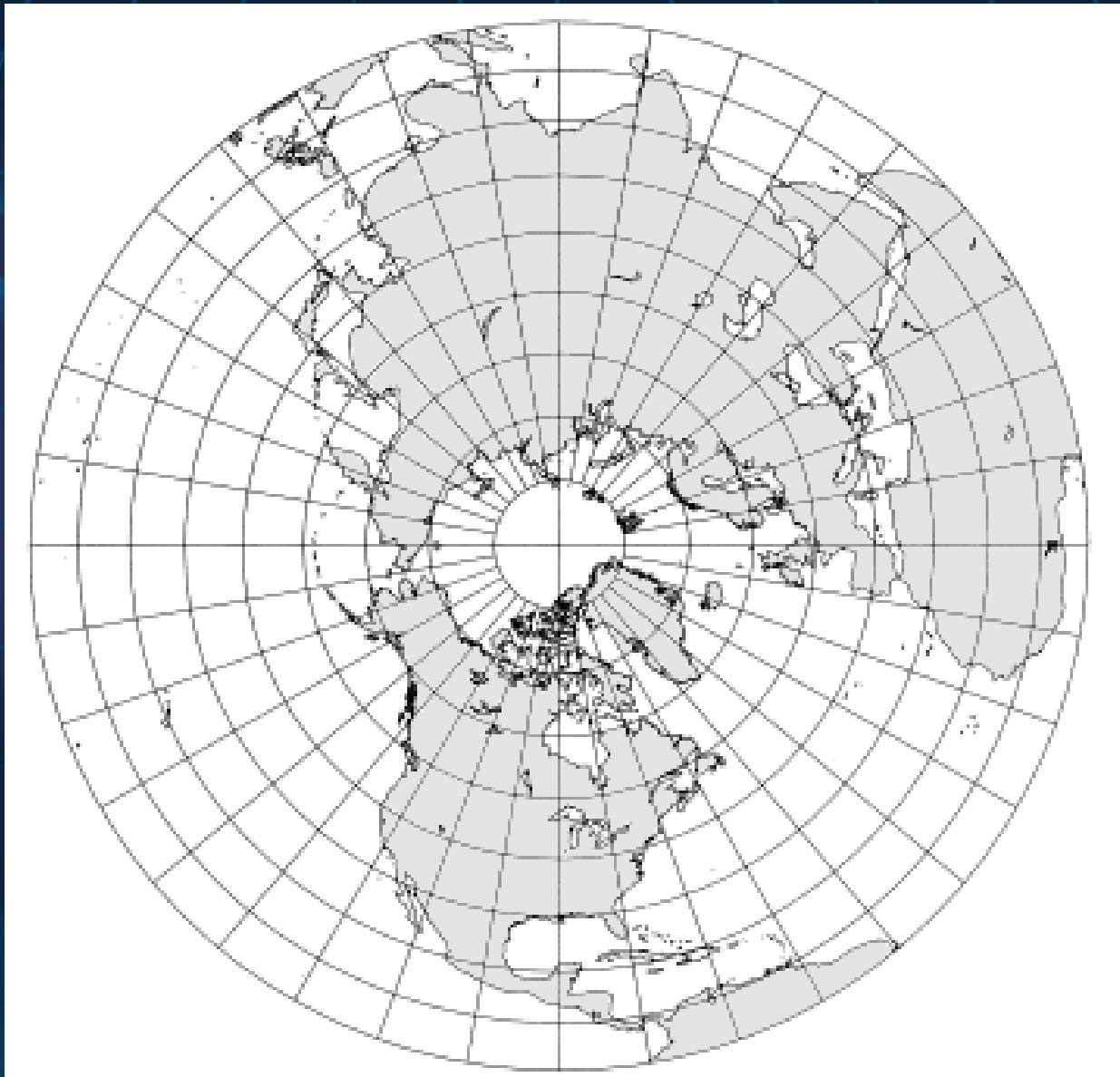
- meridians – a bundle of straight lines
- parallels – concentric circles
- pole – a circle or point

They are used for the territory around the (cartographic) pole, which is the center of the projection.

A number of them can be derived geometrically

With a suitable choice of the constant, we get individual azimuthal projections  
(equidistant, equivalent, conformal  
× pole rendition)

# Equivalent azimuthal projection



# Azimuthal projection

